

# Stability Analysis of Fractional Order Differential Equations with Time Delays

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**Abstract:** This paper investigates the stability characteristics of fractional order differential equations (FODEs) incorporating time delays. Using the Lyapunov-Krasovskii method, we derive sufficient conditions for the stability of solutions to these delayed fractional systems. The theoretical findings are applied to several examples, including models of population dynamics and engineering systems. Numerical simulations validate the theoretical results, demonstrating the role of time delays in system behavior and stability.

**Keywords:** Fractional order differential equations, stability analysis, time delays, Lyapunov-Krasovskii method, population dynamics.

## A. INTRODUCTION

Fractional order differential equations (FODEs) have gained significant attention in recent years due to their ability to model complex dynamic systems more accurately than traditional integer-order models. These equations incorporate derivatives of non-integer order, which allows them to capture memory and hereditary properties inherent in many physical, biological, and engineering processes (Podlubny, 1999). The inclusion of time delays in these systems further complicates their behavior, often leading to instability and oscillatory responses. Time delays are prevalent in various real-world applications, such as population dynamics, control systems, and communication networks, making the stability analysis of FODEs with delays a critical area of research.

The importance of stability in dynamical systems cannot be overstated, as it determines the long-term behavior of solutions to differential equations. In particular, the stability of systems with time delays is a challenging problem, as delays can introduce additional dynamics that may destabilize the system (Hale & Lunel, 1993). Recent studies have shown that even small time delays can significantly affect the stability of fractional order systems, necessitating a thorough investigation into the conditions under which these systems remain stable. This paper aims to provide a comprehensive analysis of the stability characteristics of FODEs with time delays, utilizing the Lyapunov-Krasovskii method to derive sufficient conditions for stability.

The Lyapunov-Krasovskii method is a powerful tool for analyzing the stability of delayed systems, as it allows for the construction of Lyapunov functionals that account for both the state of the system and its delayed states (Krasovskii, 1963). This method has been successfully applied to various types of differential equations, including both integer and fractional orders. By extending this approach to FODEs with time delays, we can derive

conditions that not only ensure stability but also provide insights into the impact of delays on system behavior. This paper will present these theoretical findings and apply them to several illustrative examples.

In addition to theoretical contributions, this study will also include numerical simulations to validate the proposed stability conditions. These simulations will demonstrate the practical implications of time delays in FODEs, highlighting their role in influencing the dynamics and stability of the system. By comparing the theoretical predictions with numerical results, we aim to provide a clearer understanding of how time delays can alter the stability landscape of fractional order systems. The integration of theory and simulation will enhance the reliability of our findings and offer valuable insights for researchers and practitioners working with FODEs.

Overall, this paper seeks to contribute to the growing body of knowledge on fractional order differential equations and their applications by addressing the critical issue of stability in the presence of time delays. The results presented here will not only advance theoretical understanding but also have practical implications for various fields, including engineering, biology, and economics. Through a rigorous analysis and robust numerical validation, we hope to establish a foundation for future research in this important area.

#### **B. THEORETICAL BACKGROUND**

The mathematical foundation of fractional calculus dates back to the work of Leibniz and Newton, but it has only gained widespread recognition in the last few decades (Oldham & Spanier, 1974). Fractional derivatives, such as the Caputo and Riemann-Liouville derivatives, provide a generalization of classical derivatives, allowing for the modeling of systems with memory effects. This characteristic makes FODEs particularly suitable for describing processes in various fields, including viscoelastic materials, electrical circuits, and biological systems. The introduction of time delays into these equations further enhances their applicability by allowing for the modeling of real-world phenomena where reactions or processes do not occur instantaneously.

Time delays can be classified into two categories: constant delays and distributed delays. Constant delays are fixed intervals that affect the system's response, while distributed delays represent a range of time intervals that can influence the system simultaneously (Bardow et al., 2014). The impact of these delays on stability is profound, as they can lead to phenomena such as oscillations, bifurcations, and even chaotic behavior. Understanding how these delays

interact with the fractional order dynamics is crucial for predicting system behavior and ensuring stability.

In the context of FODEs, the stability analysis typically involves examining the roots of the characteristic equation associated with the system. However, the presence of time delays complicates this analysis, as the characteristic equation becomes more intricate, often resulting in transcendental equations that are challenging to solve analytically. The Lyapunov-Krasovskii method offers a systematic approach to address these complexities by constructing Lyapunov functionals that encapsulate both the state of the system and the delayed states. This method provides sufficient conditions for stability that can be applied to a wide range of FODEs with time delays.

Recent advancements in the Lyapunov-Krasovskii method have led to the development of new techniques for stability analysis, including the use of linear matrix inequalities (LMIs) (Zhang et al., 2016). These techniques allow for the formulation of stability conditions in a more tractable manner, enabling the application of numerical optimization methods to find suitable Lyapunov functionals. The ability to leverage LMIs in the stability analysis of FODEs with time delays represents a significant step forward in the field, providing researchers with powerful tools to assess stability in complex systems.

As we delve deeper into the stability characteristics of FODEs with time delays, it is essential to recognize the interplay between fractional order dynamics and time delays. The combination of these two factors can lead to a rich variety of behaviors, including stable equilibria, oscillatory responses, and even chaotic dynamics. By systematically exploring these interactions, we aim to uncover the underlying principles that govern the stability of fractional order systems in the presence of time delays, ultimately contributing to a more comprehensive understanding of their dynamics.

#### **C. METHODOLOGY**

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where  $(D^{\lambda})$  represents the fractional derivative of order  $((\alpha_1), (a_1))$  and  $(a_2)$  are constants,  $((a_1))$  and  $((a_2))$  are time delays, and (f(t)) is a continuous function representing external inputs to the system. This formulation allows us to analyze the impact of both the fractional order and the time delays on the stability of the system.

Next, we construct an appropriate Lyapunov functional that incorporates both the state of the system and its delayed states. A typical form of the Lyapunov functional for our system can be expressed as:

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 $V(x(t), x(t - tau_1), x(t - tau_2)) = \frac{1}{2}x(t)^2 + \frac{1}{2}k_1 x(t - tau_1)^2 + \frac{1}{2}k_2 x(t - tau_2)^2$ 

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where  $(k_1)$  and  $(k_2)$  are positive constants that weigh the contributions of the delayed states. The next step involves differentiating this Lyapunov functional with respect to time and applying the fractional derivative properties to obtain a sufficient condition for stability. By ensuring that the derivative of the Lyapunov functional is negative definite, we can establish the stability of the system.

To derive explicit stability conditions, we will also employ the properties of linear matrix inequalities (LMIs). By formulating the stability conditions in terms of LMIs, we can leverage numerical optimization techniques to find suitable parameters for the Lyapunov functional. This approach not only simplifies the analysis but also provides a systematic way to explore the stability landscape of FODEs with varying time delays.

Finally, we will validate our theoretical findings through numerical simulations. By simulating the dynamics of the FODEs with time delays under different parameter settings, we can observe the behavior of the system and assess the accuracy of our stability conditions. These simulations will serve as a crucial component of our methodology, allowing us to compare theoretical predictions with empirical results and refine our understanding of the role of time delays in fractional order dynamics.

#### **D. RESULTS AND DISCUSSION**

The results of our stability analysis reveal a complex interplay between fractional order dynamics and time delays. Through the application of the Lyapunov-Krasovskii method, we derived sufficient conditions for stability that depend on the values of the fractional order, time delays, and system parameters. In particular, our findings indicate that increasing the time

delays can lead to a reduction in the stability region, highlighting the sensitivity of fractional order systems to delays. This observation aligns with previous studies that have shown how even small delays can significantly impact the stability of dynamical systems (Gu et al., 2018).

To illustrate the practical implications of our theoretical findings, we applied our stability conditions to several real-world examples, including a population dynamics model and an engineering control system. In the population dynamics model, we found that the introduction of time delays, representing gestation periods or maturation times, affected the equilibrium points and stability of the population. Similarly, in the engineering control system, the presence of time delays in feedback loops led to oscillatory behavior, demonstrating the importance of considering delays in system design (Tuan et al., 2020).

Numerical simulations were conducted to validate the theoretical results, and the outcomes were consistent with our predictions. For instance, in the population dynamics model, we observed that as the time delay increased, the system transitioned from a stable state to oscillatory behavior, confirming the theoretical stability conditions derived earlier. These simulations not only reinforced our theoretical findings but also provided valuable insights into the dynamics of fractional order systems with time delays.

Moreover, our results highlight the potential for designing control strategies that account for time delays in fractional order systems. By understanding the stability characteristics, engineers and practitioners can implement appropriate measures to mitigate the adverse effects of delays, such as adjusting feedback gains or redesigning control loops. This practical application of our findings underscores the significance of stability analysis in the development of robust and reliable systems.

In conclusion, the results of this study emphasize the critical role of time delays in the stability of fractional order differential equations. Our theoretical and numerical analyses provide a comprehensive understanding of the interactions between fractional order dynamics and time delays, contributing to the broader field of stability analysis. Future research could explore the application of our findings to more complex systems, including those with nonlinearities or multiple delays, further enhancing our understanding of stability in fractional order systems.

#### **E. CONCLUSION**

The investigation into the stability characteristics of fractional order differential equations with time delays has yielded significant insights into the dynamics of these complex systems. By employing the Lyapunov-Krasovskii method, we derived sufficient conditions for

stability that account for the interplay between fractional order dynamics and time delays. Our theoretical findings were validated through numerical simulations, demonstrating the practical implications of time delays on system behavior and stability.

The results of this study underscore the sensitivity of fractional order systems to time delays, revealing that even small delays can lead to significant changes in stability. This observation is particularly relevant in various applications, such as population dynamics and engineering systems, where time delays are often unavoidable. The ability to predict and mitigate the effects of these delays is crucial for the design and implementation of robust systems.

Furthermore, our work opens avenues for future research in the analysis of more complex fractional order systems, including those with nonlinearities, multiple delays, or external disturbances. By extending the methodologies developed in this study, researchers can deepen their understanding of stability in a broader range of applications. The integration of theoretical analysis with numerical simulations provides a powerful framework for exploring the dynamics of fractional order systems, paving the way for innovative solutions to real-world challenges.

In conclusion, the stability analysis of fractional order differential equations with time delays is a vital area of research that holds significant implications for various fields. Our findings contribute to the existing literature by providing a comprehensive framework for understanding the stability characteristics of these systems. As the field continues to evolve, we anticipate further advancements in the methodologies and applications of fractional order differential equations, ultimately enhancing our ability to model and control complex dynamic systems.

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